

# Nonlinear Dynamical Systems and Control

## Errata and Addenda

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This document contains an updated list of errata and addenda. Please e-mail us if you discover additional typos or errors, and we will include them in future updates.

- Page xxv, 2nd paragraph, line 1: replace “Heraklitos” with “Herakleitos”.
- Page 2, Definition 1.1, statement  $v$ ): replace statement with “For every  $x_0 \in \mathcal{D}$ ,  $u \in \mathcal{U}$ , and  $t_0 \in \mathbb{T}$ , there exists  $y \in \mathcal{Y}$  such that  $y(t) = h(t, s(t, t_0, x_0, u), u(t))$  for all  $t \in \mathbb{T}$ .”
- Page 22, Example 2.5: replace “ $\mathcal{B}_\varepsilon(0) \subseteq \mathcal{S}$ ” with “ $\mathcal{B}_\varepsilon(x) \subseteq \mathcal{S}$ .”
- Page 45, 2nd line above Example 2.19: delete statement  $iii$ ).
- Page 49, Example 2.22: delete the wording “since  $f'$  is unbounded in every neighborhood of the origin.”
- Page 71, Definition 2.47, statement  $i$ ): replace “for every  $t \in \mathbb{R}$ ,  $s(\cdot, x)$  is continuously differentiable on  $\mathcal{D}$ .” with “for every  $x \in \mathcal{D}$ ,  $s(\cdot, x)$  is continuously differentiable on  $\mathbb{R}$ .”
- Page 103, line 20: change “ $\mathcal{O}_{x_0}^+$ ” to “ $\mathcal{C}$ ”
- Page 103, line 22: change “ $\mathcal{O}_{x_0}^+$ ” to “ $\mathcal{C}$ ”
- Page 106, line 4 after Definition 2.54: change “ $\mathcal{G}$ ” to “ $\mathbb{T}$ ”
- Page 106, Theorem 2.44: delete the wording “such that there are no equilibrium points of (2.230) and (2.231) in  $\mathcal{D}$ ” and add the wording “other than equilibrium points” at the end of the theorem statement.

- Page 109, Theorem 2.45: delete the wording “such that there are no equilibrium points of (2.230) and (2.231) in  $\mathcal{D}$ ” and add the wording “other than equilibrium points” at the end of the theorem statement.
- Page 117, Problem 2.50, Equation (2.251): replace “ $x \in \mathcal{D}$ ” with “ $y \in \mathcal{D}$ .”
- Page 125, Problem 2.106, line 2 and line 6: change “(2.211)” to “(2.212)”
- Page 130, Problem 2.139: replace Equations (2.287) and (2.288) with

$$\begin{aligned}\dot{x}_1(t) &= x_2(t), & x_1(0) &= x_{10}, & t &\geq 0, \\ \dot{x}_2(t) &= -x_1(t) + x_2(t)[1 - x_1^2(t) - 2x_2^2(t)], & x_2(0) &= x_{20}.\end{aligned}$$

- Page 130, Problem 2.142, Equations (2.294) and (2.295): change “ $[\beta^2 - x_1(t) - x_2^2(t)]^\gamma$ ” to “ $[\beta^2 - x_1^2(t) - x_2^2(t)]^\gamma$ ”
- Page 150, Example 3.6, line 2: change “notion” to “motion”
- Page 185, Problem 3.16, Equation (3.218): change “ $u_i(t)$ ” to “ $-u_i$ ”
- Page 186, Problem 3.17, Equation (3.220): replace “ $\frac{1}{2}(\theta^2 + \dot{\theta}^2)$ ” with “ $\frac{1}{2}(\theta^2 + a\dot{\theta}^2)$ ”
- Page 195, Problem 3.44, 1st line in hint: replace “positive orbit  $\mathcal{O}_x^+$ ” with “positive limit set  $\omega(x)$ ”
- Page 195, Problem 3.45: replace “ $A \in \mathbb{R}^n$ ” with “ $A \in \mathbb{R}^{n \times n}$ .”
- Page 261, Proposition 4.7, 2nd and 3rd lines: replace “positive orbit  $\mathcal{O}_x^+$ ” with “positive limit set  $\omega(x)$ ” and “ $\mathcal{O}_x^+ = \{y\}$ ” with “ $\omega(x) = \{y\}$ ”
- Page 261, proof of Proposition 4.7, lines 1, 4, and 7: replace “ $y \in \mathcal{O}_x^+$ ” with “ $y \in \omega(x)$ ” and “ $\mathcal{O}_x^+ = \{y\}$ ” with “ $\omega(x) = \{y\}$ ”
- Page 265, Theorem 4.21, line 4: replace “class  $\mathcal{K}$  function” with “class  $\mathcal{K}_\infty$  function”
- Page 266, line 1: replace “ $ii$  holds.” with “ $ii$  holds with  $\alpha(r) = r$ .”
- Page 319, Problem 4.29, 2nd line in statement  $ii$ ): change “continuous at  $(t, 0)$ ” to “jointly continuous at  $(t, 0)$ ”

- Page 320, 2nd line: change “continuous at  $(t, 0)$ ” to “jointly continuous at  $(t, 0)$ ”
- Page 321, Problem 4.33 line 6: change the set “ $\{(x_1, x_2) \in \mathbb{R}^2 : \frac{1}{2}x_1^2 + x_2^2\}$ ” to “ $\{(x_1, x_2) \in \mathbb{R}^2 : \frac{1}{4}x_1^2 + x_2^2\}$ ”
- Page 321, Problem 4.34: change “ $2 \sin 2t$ ” to “ $\sin 2t$ ”
- Page 321, Problem 4.36, Equation (4.427): change “ $4x_1$ ” to “ $4x_1(t)$ ”
- Page 335, 2nd and 3rd lines in the proof of Theorem 5.3: change “there exists  $x \in \mathcal{D}$ ” to “there exists  $x \in \mathcal{D}, x \neq 0$ ,” and replace “ $r(u(t), y(t)) = 0$  almost everywhere  $t \geq 0$ , for all admissible  $u(\cdot) \in \mathcal{U}$ .” with “ $r(u(t), y(t)) = 0$  almost everywhere  $t \geq 0$ , for  $u(t) = \kappa(y(t))$ ”.
- Page 345, Equation (5.71): change “ $(\frac{\partial \mathcal{H}}{\partial x}(x))$ ” to “ $(\frac{\partial \mathcal{H}}{\partial x}(x))^T$ ”
- Page 348, 3rd line after Equation (5.85): change “ $\ell : \mathbb{R}^n \rightarrow \mathbb{R}$ ” to “ $\ell : \mathbb{R}^n \rightarrow \mathbb{R}^p$ ”
- Page 350, LHS of Equation (5.94): change “ $y(s)ds$ ” to “ $y(s))ds$ ”
- Page 362, 1st line after Equation (5.163): change “ $\gamma^2$ ” to “ $\gamma$ ”
- Page 363, line 4: change “Definition 5.19” to “Definition 5.18”
- Page 376, last line before Equation (5.209): change “if” to “it”
- Page 378, line 7: replace “ $\sigma_s(y, t) = \sigma(y, t) - M_1(y)$ ” with “ $\sigma_s(y, t) = \sigma(y, t) - M_1 y$ ”
- Page 386, Figure 5.9: change “Popov slope =  $-1/N$ ” to “Popov slope =  $1/N$ ”
- Page 394, Equation (5.253): replace “ $\lambda$ ” with “1”
- Page 396, Problem 5.34, line 4: replace “Show that the following statements are equivalent:” with “Consider the following statements:” In addition, after Equation (5.261) add “Show that *i*) and *ii*) are equivalent, *iii*) and *iv*) are equivalent, and *i*) (or, equivalently, *ii*) implies *iii*) (or, equivalently, *iv*).”

- Page 401, line 1: change “ $C(q, \dot{q})_{(i,j)} = \sum_{k=1}^n \gamma_{ijk}(q)\dot{q}_k$ , where  $i, j = 1, \dots, n$ ” with “ $C(q, \dot{q})_{(k,j)} = \sum_{i=1}^n \gamma_{ijk}(q)\dot{q}_i$ , where  $k, j = 1, \dots, n$ ”
- Page 405, Problem 5.57, line 1: change “Matheiu” to “Mathieu”
- Page 439, Example 6.5: replace “ $\inf_{u \in U}$ ” with “ $\inf_{u \in \mathbb{R}}$ ”
- Page 492, Proof of Theorem 7.7, lines 5 and 6 in statement *i*): replace

$$\begin{aligned} & \leq \sup_{\omega \in \mathbb{R}} \sigma_{\max}(H(j\omega)) \frac{1}{2\pi} \int_{-\infty}^{\infty} u^*(j\omega)u(j\omega)d\omega \\ & = \sup_{\omega \in \mathbb{R}} \sigma_{\max}(H(j\omega)) \|u\|_{2,2}^2, \end{aligned}$$

with

$$\begin{aligned} & \leq \left( \sup_{\omega \in \mathbb{R}} \sigma_{\max}(H(j\omega)) \right)^2 \frac{1}{2\pi} \int_{-\infty}^{\infty} u^*(j\omega)u(j\omega)d\omega \\ & = \left( \sup_{\omega \in \mathbb{R}} \sigma_{\max}(H(j\omega)) \right)^2 \|u\|_{2,2}^2, \end{aligned}$$

- Page 532, Equation (8.113): change “ $x_1(t) + x_1(t)x_2^2(t)$ ” to “ $-x_1(t) + x_1(t)x_2^2(t)$ ”
- Page 532, Equation (8.116): change “ $\frac{1}{2}V'(x)$ ” to “ $\frac{1}{2}V'(x)$ ”
- Page 532: replace Equation (8.117) with

$$[2x_1 \ 2x_2] \begin{bmatrix} -x_1 + x_1x_2^2 \\ -x_2 - 2x_1^2x_2 \end{bmatrix} = -2(x_1^2 + x_2^2 + x_1^2x_2^2) < 0$$

- Page 543, Equation (8.156): change “ $\alpha(x(t))$ ” to “ $-\alpha(x(t))$ ” and “ $-\frac{\gamma(x(t))}{2}\beta^T(x(t))\beta(x(t))$ ” to “ $\frac{\gamma(x(t))}{2}\beta^T(x(t))\beta(x(t))$ ”
- Page 817, 1st line after Equation (13.200): change “ $\gamma^2$ ” to “ $\gamma$ ”
- Page 943, 3rd column, line 21: replace “theotem” with “theorem”